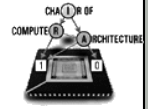


Conflict-Based Selection of Branching Rules in SAT Algorithms

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Where do we come from?



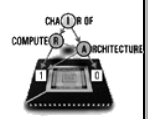
- South-west Germany
- Freiburg
- Black Forest
- near Rhein river
- near France and Suisse





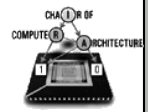
What is our interest in SAT?

- Research focus on VLSI topics
 - Testing
 - Verification
 - Logic Synthesis
 - Routing
- Basic data structures and algorithms:
 - Decision Diagrams (BDDs, OKFDDs, K*BMDs, ...)
 - SAT (general SAT, structural SAT, ...)
 - ...



Overview

- Introduction
- SAT Applications
- SAT Algorithm
- Branching Rules
- Adaptive Framework
- Experimental Results
- Conclusions



SAT Algorithms: New Features

- Intelligent Branching Rules
- Preprocessing
- Conflict analysis techniques
 - Non-chronological Backtracking
 - Conflict Learning
- Restarts
- Algorithm Portfolio



Branching Rules: Comparison

Branching Rule	Time	Aborts
Böhm	1817,45	8
MOM	1428,04	7
OS-J W	807,82	4
TS-J W	911,28	4
DLCS	746,3	3
DLIS	409,14	1
RDLIS	439,16	1,1
RAND	1431,85	5,7

Conclusion: DLIS gets best results

Observation: But still instance specific differences

- ➔ no general best-of-all branching rule
- ➔ variable selection in DP is NP-/coNP-hard (Liberatore, 2000)



Conflict Analysis (4/4)

- 1UIP scheme stops at R_4
- v_{10} last literal from DL 7 in R_4
- next „lower“ in R_4 : $v_{19}=0$ @ DL 3
- R_4 triggers $v_{10}=1$ @ DL 3
- Nonchronological backtracking to DL 3

Assume ($v_{11}=1$) @ DL 7:

- $v_{12}=0$ due to c_1
- $v_{16}=1$ due to c_2
- $v_2=0$ due to c_3
- $v_{10}=0$ due to c_4
- $v_1=1$ due to c_5
- $v_3=1$ due to c_6
- $v_5=0$ due to c_7
- $v_{18}=1$ due to c_8
- conflict at c_9 due to v_{18}

Resolution ↑

$$\text{Res}(v_1, R_3, c_5) = (-v_8, +v_{10}, +v_{17}, +v_{19}) \quad [R_4]$$

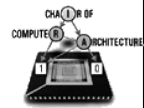
$$\text{Res}(v_3, R_2, c_6) = (-v_1, +v_{10}, +v_{17}, +v_{19}) \quad [R_3]$$

$$\text{Res}(v_5, R_1, c_7) = (-v_1, -v_3, +v_{10}, +v_{17}, +v_{19}) \quad [R_2]$$

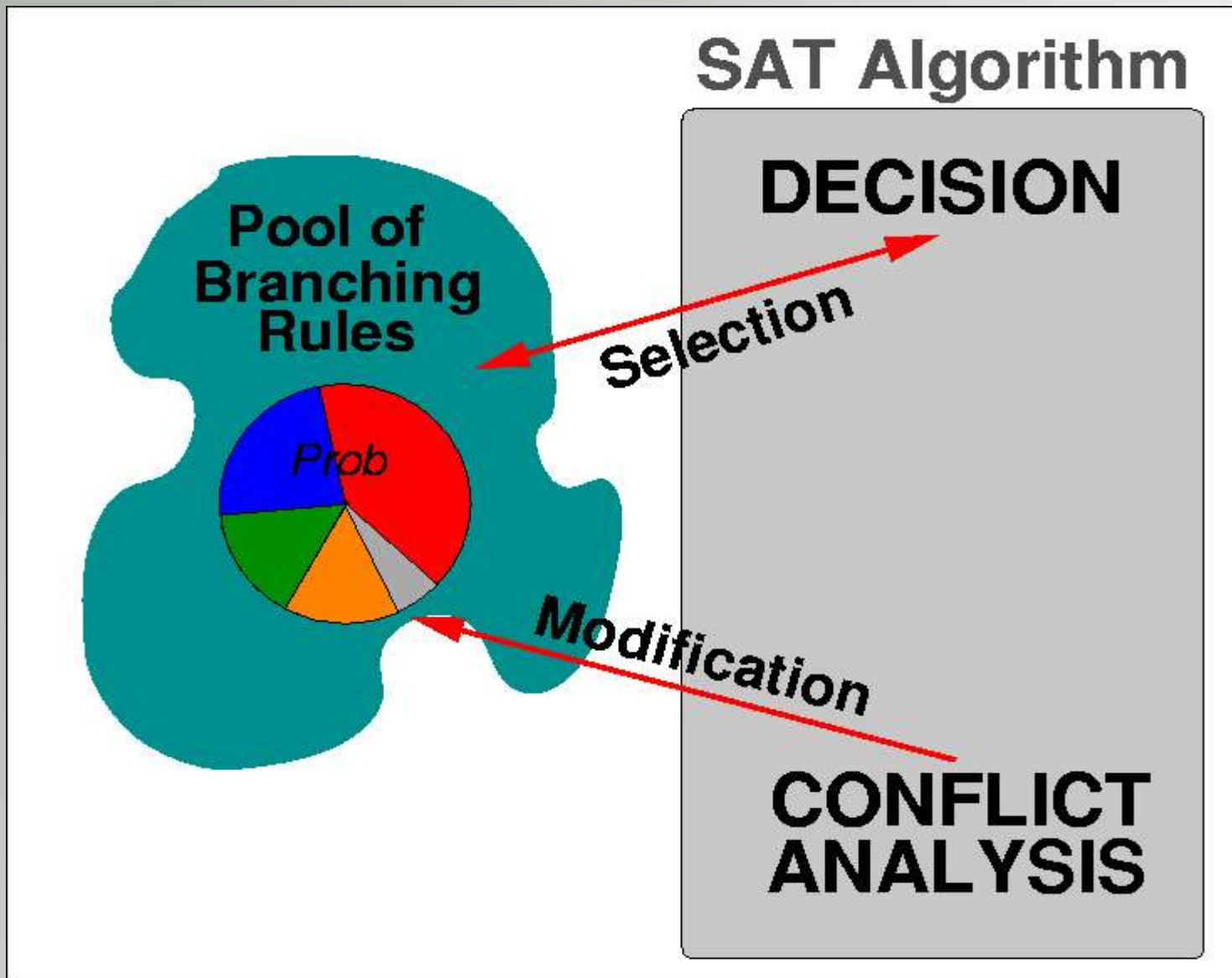
$$\text{Res}(v_{18}, c_9, c_8) = (-v_1, -v_3, +v_5, +v_{17}, +v_{19}) \quad [R_1]$$



Adaptive Framework



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Adaptive Framework

Features of our approach:

- Set of Branching Rules: $B = \{\rho_1, \dots, \rho_t\}$
- Attach preference value $Pref(\rho_i)$ where
$$0 \leq Pref(\rho_i) \leq 1$$
$$\sum Pref(\rho_i) = 1$$
- Branching Rule selection methods
- Conflict-based adaption of preference values



Selection Methods

3 selection methods

(known from theory of Genetic Algorithms):

- Roulette-Wheel (RW):

$$\rightarrow Prob(\rho) = Pref(\rho)$$

- Linear Ranking (LR):

$$\rightarrow Prob(\rho) = Rank(\rho, B) \cdot \frac{2}{(n \cdot (n + 1))}$$

- k -Tournament (2T):

→ select randomly k elements from $B, B_k \subset B$

→ select $\rho_{sel} \in B_k$ with maximum preference value

$$\rightarrow Pref(\rho_{sel}) = \max_{\rho \in B_k} (Pref(\rho))$$



Adaption of Preferences (1/5)

Observation

Conflicts are

- mandatory in unsatisfiable SAT instances to reduce search costs
- unessential in satisfiable SAT instances since search path without conflicts exists

Problem

How to determine solvability of SAT instance?



Adaption of Preferences (2/5)

Definition (Individual Averaged #C/#V Ratio):

For SAT instance I , set at the beginning

$$AR(I) = \frac{NoOfClauses(I)}{NoOfVariables(I)}$$

During search, after each conflict, update

$$AR_{new}(I) = \frac{1}{2} \cdot \left(AR_{old} + \frac{NoUnresolvedClauses(I)}{NoFreeVariables(I)} \right)$$

Now:
If $\frac{NoUnresolvedClauses(I)}{NoFreeVariables(I)} \leq AR_{old}(I)$

- relatively less constrained
- punishing mode

else

- relatively more constrained
- reward mode



Adaption of Preferences (3/5)

Definition (Conflict-triggering branching rule):

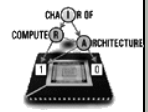
BR $\rho \in B$ triggers a conflict iff

- (1) A conflict occurs on decision level d
- (2) Non-chronological backtracking backtracks to d'
- (3) ρ was applied at decision level d'

Keep 2 counters for each branching rule ρ :

Used(ρ) = number of applications of ρ

Trigger(ρ) = number of conflicts triggered by ρ



Adaption of Preferences (4/5)

Now we can dynamically adapt preferences when ρ triggered a conflict:

$$Update(\rho) = 1 + (-1)^{mode} \cdot \frac{Trigger(\rho)}{Used(\rho)}$$
$$Pref_{new}(\rho) = Update(\rho) \cdot Pref_{old}(\rho)$$

($mode=1$ in punishing mode, $mode=0$ in reward mode)

- ➔ preference is decreased in punishing mode
- ➔ preference is increased in reward mode



Adaption of Preferences (5/5)

What else must be done?

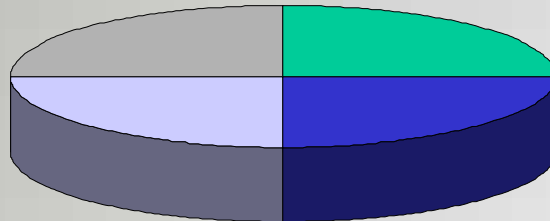
- Difference distribution after update of preference
 - uniform/weighted distribution
- Suitable initialization values
 - Ranking of single-branching rule experiments wrt Time, #Aborts, both
 - Time-Rank, Abort-Rank, Time-Abort-Rank
 - we restrict to Abort-Rank
(minimizing aborts has highest priority, gave best results!)



Difference Distribution

After update of preference value, difference between old and new preference must be distributed to the other branching rules!

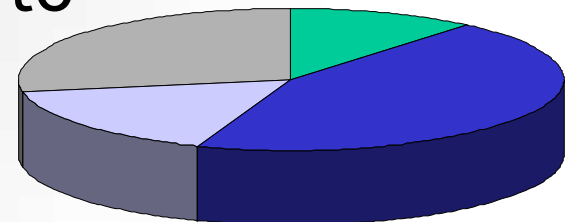
- Uniform:



each gets the same portion

- Weighted:

each gets a portion proportional to its own preference value





Experiments (1): Benchmarks

Name	# var	# clauses	status
bw_large.c	3016	50457	sat
bw_large.d	6325	131973	sat
e0ddr2-19-by-5-1	19500	103887	sat
e0ddr2-19-by-5-4	19500	104527	sat
enddr2-10-by-5-1	20700	111567	sat
enddr2-10-by-5-8	21000	113729	sat
ewddr2-10-by-5-1	21800	118607	sat
ewddr2-10-by-5-8	22500	123329	sat
hfo3.010.1	215	920	sat
hfo3.022.1	215	920	sat
hfo3.027.1	215	920	sat
qg5-10	1000	43636	unsat
qg7-11	1331	49534	unsat



Experimental Results (1)

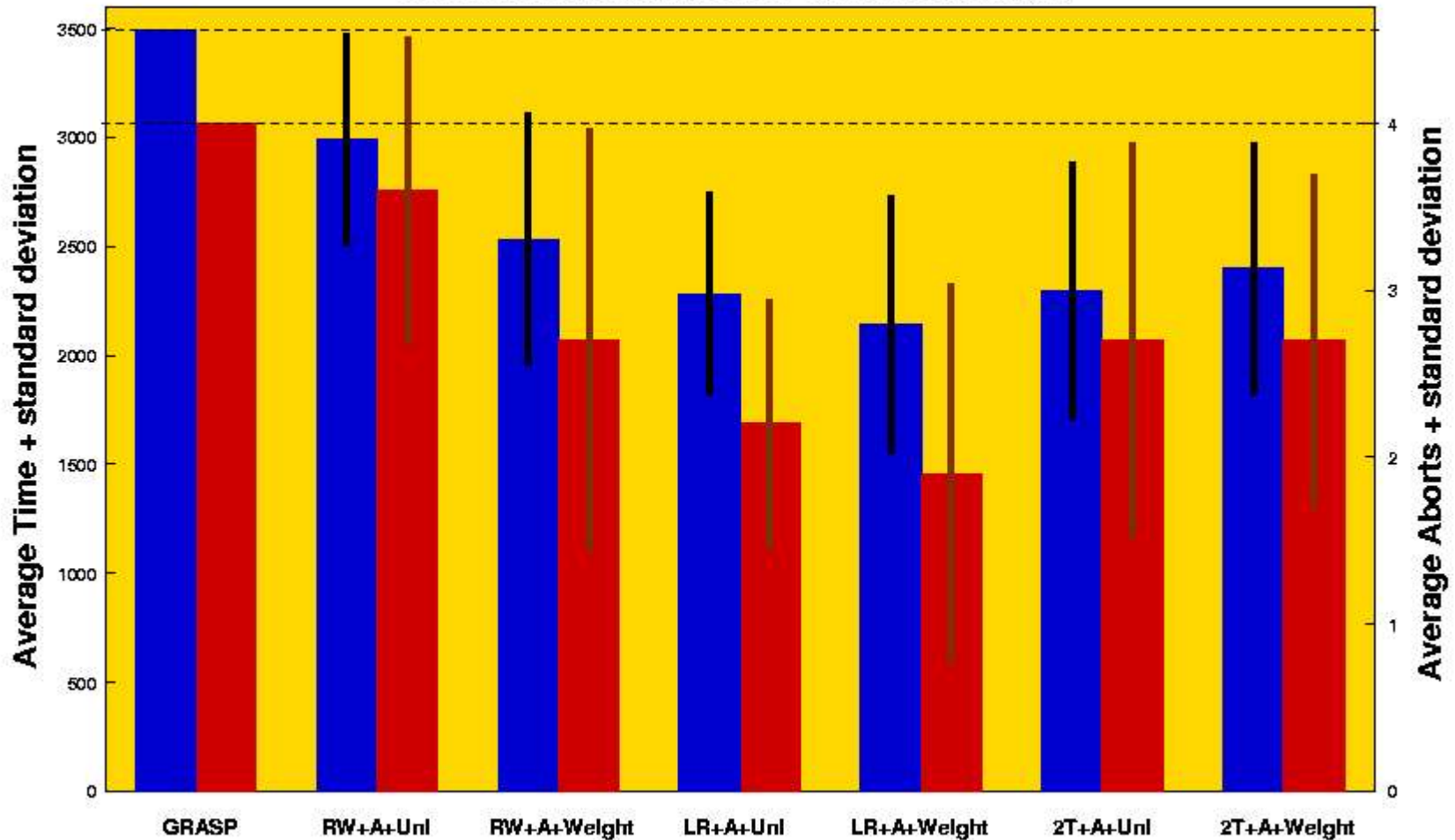
Solver	Time		Aborts	
	Avg.	Std. Dev.	Avg.	Std. Dev.
GRASP-DLIS	3492		4	
RW+ Abort+ Uni	2989	488	3,60	0,92
RW+ Abort+ weight	2531	581	2,70	1,27
LR+ Abort+ uni	2281	467	2,20	0,75
LR+ Abort+ weight	2139	594	1,90	1,14
2T+ Abort+ uni	2294	594	2,70	1,19
2T+ Abort+ weight	2398	580	2,70	1,00



Experimental Results (1)

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Results on hard GRASP benchmarks (1)





Experiments (2): Benchmarks

Name	# var	# clauses	status	GRASP
4blocks	758	47820	sat	1524.62
bw_large.d	6325	131973	sat	3002.47
c7552_bug	7559	20109	sat	94.16
hfo5.032.1	55	1163	sat	2826.72
hfo6.018.1	40	1745	sat	3000.82
hfo6.020.1	40	1745	sat	3000.70
barrel5	1407	5383	unsat	950.36
hfo3.002.0	215	920	unsat	3000.78
hfo3.015.0	215	920	unsat	3000.50
hfo3.035.0	215	920	unsat	3000.45
hfo3.039.0	215	920	unsat	3000.65
qg5-10	1000	43636	unsat	1011.89
qg6-11	1331	49204	unsat	1595.54
qg7-11	1331	49534	unsat	1278.77

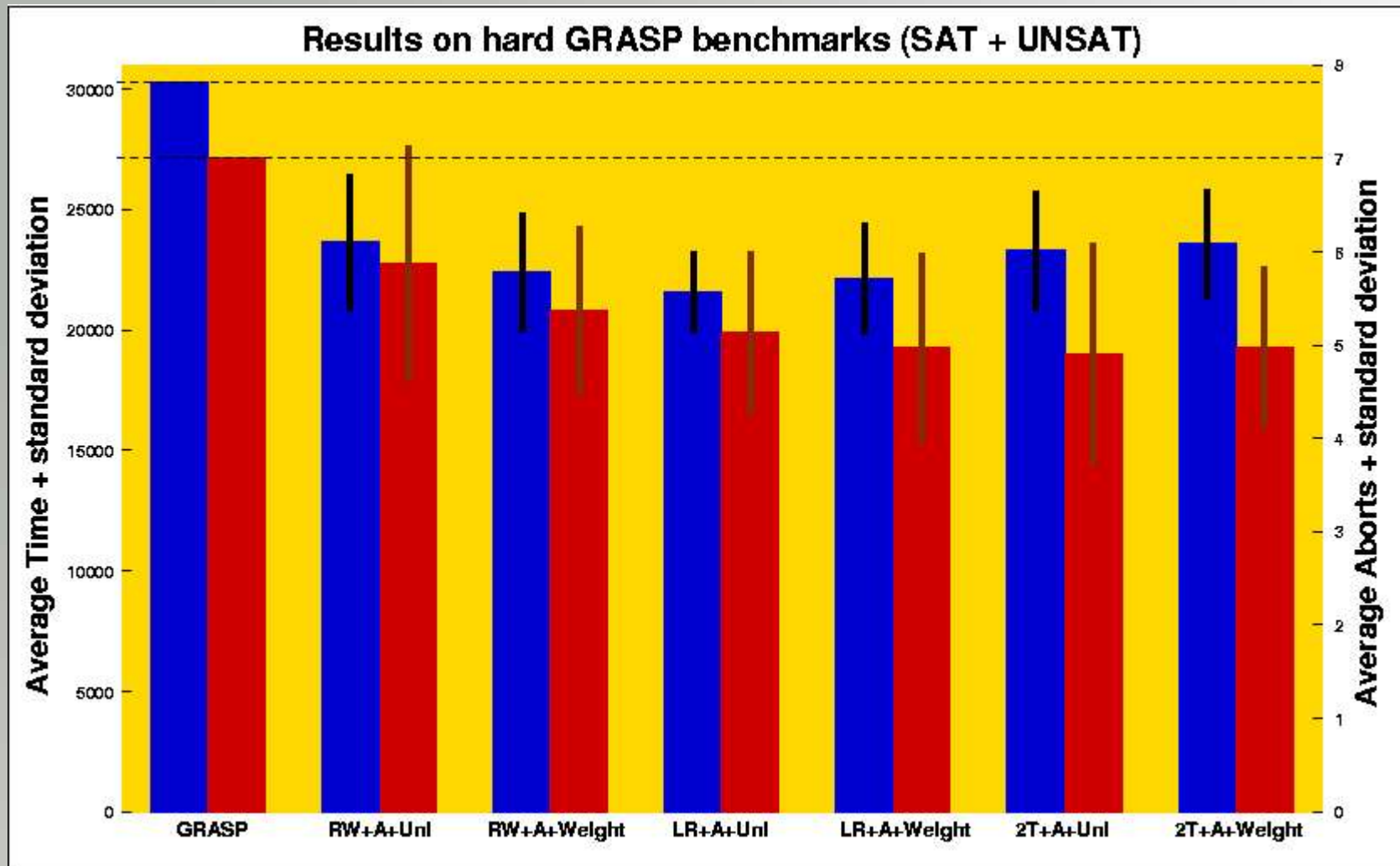
Machine: Intel Xeon 2Ghz, 2GB RAM

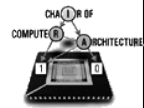
Time limit: 3000sec



Experimental Results (2)

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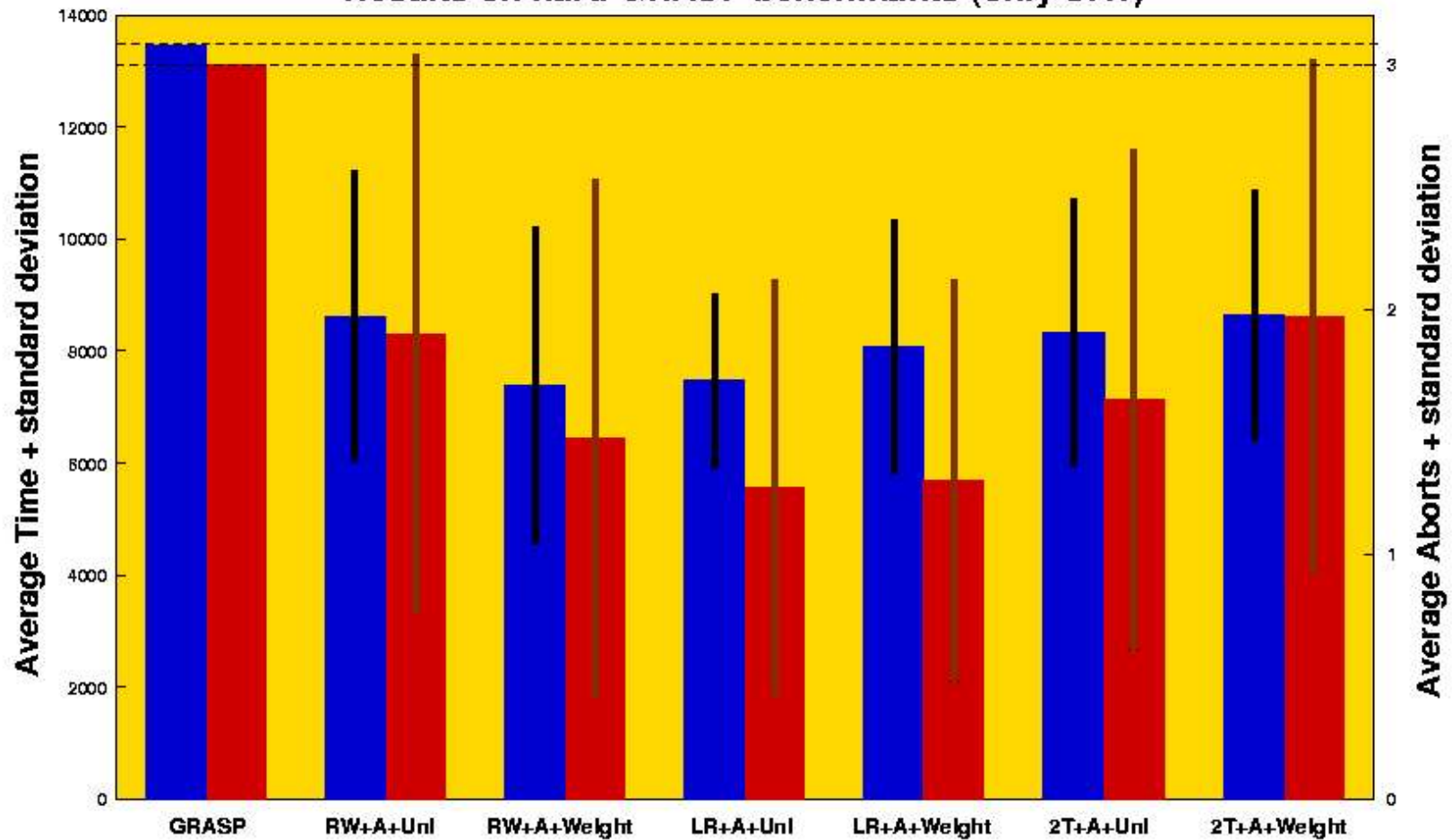


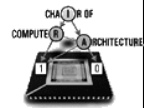


Experimental Results (2)

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Results on hard GRASP benchmarks (only SAT)

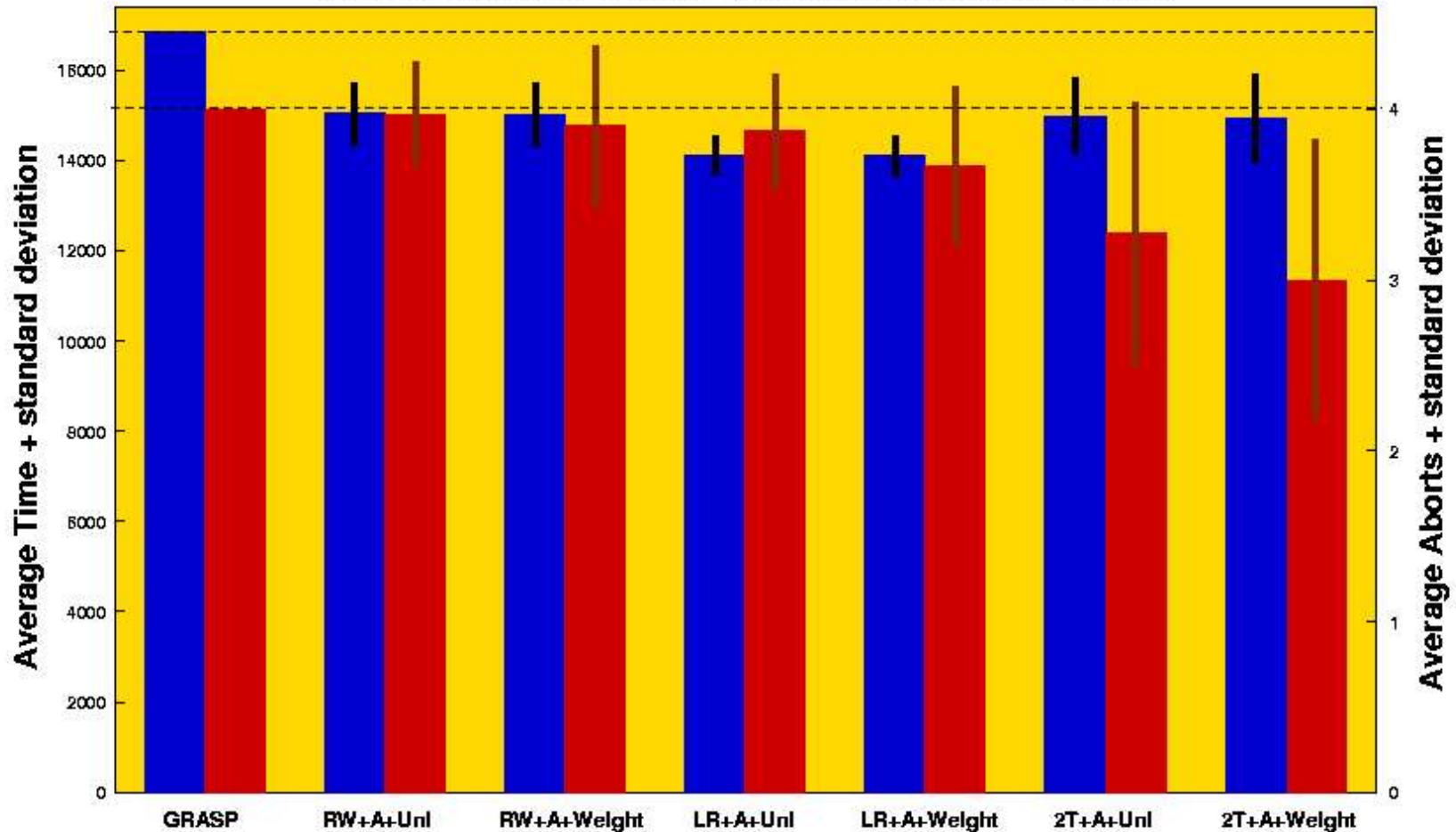




Experimental Results (2)

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Results on hard GRASP benchmarks (only UNSAT)





The times they are a changing!

- Project was initiated before Chaff
- Chaff changed a lot!
- What is the benefit of our work?
 - Solvability estimation is of high interest
 - Exploitation of several branching rules is helping
 - Seems to fit into portfolio concept and distributed computation



Future work

- Design of Chaff-like branching rules (see also BerkMin) with different flavors
- Robust solvability estimation measure
- Interaction between the SAT components
- ...



Conclusions

We presented

- an adaptive framework combining
 - ♦ multiple branching rules
 - ♦ information from conflict-analysis
- a definition to handle solvability status during SAT search

Experimental results show the feasibility.

Future work will target to transfer the framework to new class of SAT solvers (Chaff, ...)